

# **Sif**<sup>™</sup>

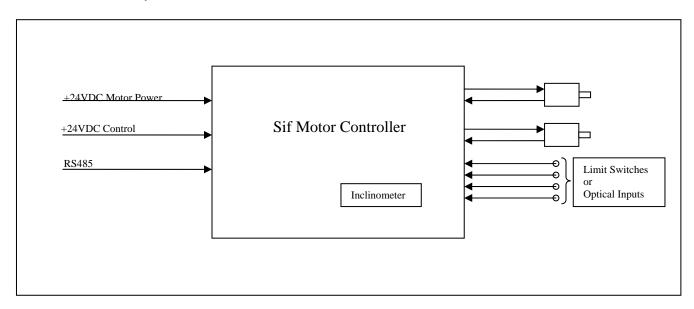
# **Solar Tracker Motor Controller**

# **Summary:**

 $Sif^{m}is$  the ideal motor controller to point a field of single or dual axis solar trackers directly at the sun for maximum energy harvesting while providing full operational accountability.

### **Features**

- Separate motor and electronics power
- Built-in high precision inclinometer
- Dual H-Bridge DC motor drivers
- Built-in motor current sensing
- Built-in support for single and dual encoders per motor
- Built-in support for single and dual limit switches per motor
- Built-in support for optional optical or potentiometer feedback
- Built-in support for emergency stop
- RS-485 optically isolated network interface
- For use with 24V DC systems
- Support for remote monitor and control
- Remote re-program capability
- Large supply voltage range
- Push buttons for manual operation
- Connector for remote control box
- Available in Polycarbonate or Aluminum enclosure



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# **Description:**

**Microprocessor Based Control:**  $Sif^{TM}$  is a cost effective, microprocessor based motor controller suitable for single or dual axis applications. It is networked via an RS-485 bus with the  $Utgard^{TM}$  Master Tracker Controller, from which it receives positional data and site management commands. The Sif controller typically operates the tracker motors in a closed loop using position feedback.

**Modulated Power Output:** Each of the two DC motor drivers contains circuitry to regulate motor power and detect overloads. Both motor voltage and current is recorded by the *Sif* controller, and made available for data upload.

**RS-485 Network Interface:** *Sif* uses the industry wide RS485 network standard as communication means. The RS485 network transceiver is electrically isolated from the main  $Utgard^{TM}$ , thus providing a high degree of protection and noise immunity. The  $Sif^{TM}/Utgard^{TM}$  communication protocol is Modbus<sup>TM</sup> based.

#### Low Voltage Power

To ease installation, the controller is operated by a dual 24V DC power supply. By using a dual supply scheme, it is possible to operate the  $Sif^{fm}$  electronics even though the motor power may be off, thus offering advanced fault diagnostics options.

#### **Sensory Inputs**

A *Sif*<sup>fm</sup> has 4 encoder, 4 limit switches, and 1 stop button inputs. The encoder inputs can be either reed switch or Hall sensory based. An optional dual analog input can be used for additional analog sensors.

### **Electrical Ratings**

Parameter	Min	Тур	Max	Units
Controller Voltage Supply	6	24	40	V
Controller Power Consumption	0.05		0.25	W
Motor Voltage Supply	10	24	40	V
Motor Current	NA	3	$10^{1}$	Α
RS-485 Isolation			2.5	KV

#### Notes:

1. Sustained motor current should not exceed 4A over a 10 minute period

#### **Thermal Characteristics**

Parameter	Min	Тур	Max	Units
Storage Temperature	-40		120	C
Operating Temperature	-10		60	C

#### **Inclinometer Characteristics**

Parameter	Value	Units
Number of Axis	2	
Absolute accuracy	<0.1	Degree
Linearity	<0.1	

2 6/16/2009

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6/16/2009

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## Mechanical

Parameter	Value	Units
Weight	1	Kg (Polycarbonate)
Dimensions	25x18x9	Cm
Enclosure	NEMA4x	Polycarbonate or
		Aluminum



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**Sif;** is the name of Thor's wife in Norse Mythology. www.lauritzen.biz

6/16/2009